

# The Arzéla-Ascoli theorem for non-locally convex weighted spaces

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## Abstract

We deal with Arzéla-Ascoli type theorems in non-locally convex weighted spaces  $CV_0(X, E)$  and  $CV_p(X, E)$ .

**Key words:** Arzéla Ascoli theorem, Weighted spaces of continuous functions

## 1 Introduction and Preliminaries

In this paper we characterize the precompact subsets of the weighted spaces  $CV_0(X, E)$  and  $CV_p(X, E)$  for an arbitrary topological vector space (TVS)  $E$ . This extends to the non-locally convex setting Arzéla-Ascoli type theorems given in [12]. Whenever the space  $E$  happens to be quasicomplete, this turns out to be characterizations of relative compactness. The importance of Arzéla-Ascoli type theorems is evident. Their applications already in the case of scalar-valued functions are numerous, namely in differential equations, in finding extremal curves, in Mazure-Orlicz criterion for the consistency of systems involving certain inequalities etc. For example, by the Arzéla-Ascoli theorem, every bounded equicontinuous sequence in  $C(X)$ , with  $X$  compact, has a uniformly convergent subsequence. This observation is very useful in the existence of solutions of differential equations. In [12], W.M. Ruess and W.H. Summers used effectively the Arzéla-Ascoli theorem for the locally convex weighted spaces to obtain a solution of the Cauchy problem

concerning the asymptotic almost periodic behavior of motion solutions. Our results may then provide a framework for further applications in the non-locally convex setting.

Throughout this paper, unless stated otherwise,  $X$  will denote a completely regular Hausdorff space and  $E$  a non-trivial Hausdorff topological vector space (TVS) with a base  $\mathcal{W}$  of closed balanced neighborhoods of 0. A *Nachbin family*  $V$  on  $X$  is a set of non-negative upper semicontinuous functions on  $X$ , called *weights*, such that given  $u, v \in V, t \geq 0$  and  $x \in X$ , there exists  $w \in V$  with  $tu, tv \leq w$  (pointwise) and  $w(x) > 0$ . Let  $C(X, E)$  be the vector space of all continuous  $E$ -valued functions on  $X$ , and  $C_b(X, E)$  (resp.  $C_p(X, E), C_0(X, E)$ ) the subspace of  $C(X, E)$  consisting of those functions which are bounded (resp. have precompact range, vanish at infinity). Further, let

$$\begin{aligned} CV_b(X, E) &= \{f \in C(X, E) : vf(X) \text{ is bounded in } E \text{ for all } v \in V\}, \\ CV_p(X, E) &= \{f \in C(X, E) : vf(X) \text{ is precompact in } E \text{ for all } v \in V\}, \\ CV_0(X, E) &= \{f \in C(X, E) : vf \text{ vanishes at infinity on } X \text{ for all } v \in V\} \end{aligned}$$

Clearly,  $CV_0(X, E) \subset CV_p(X, E) \subset CV_b(X, E)$ . The first inclusion is due to the upper semicontinuity of the weights. When  $E = \mathbb{K}$ , the above spaces are denoted by  $C(X), C_b(X), C_p(X), C_0(X), CV_b(X)$ , and  $CV_0(X)$ . If  $\varphi \in C(X)$  and  $a \in E$ , then  $\varphi \otimes a$  is the function in  $C(X, E)$  defined by  $(\varphi \otimes a)(x) = \varphi(x)a; x \in X$ . The *weighted topology*  $w_V$  [11, 4] on  $CV_b(X, E)$  is defined as the linear topology which has a base of neighborhoods of 0 consisting of all sets of the form

$$N(v, G) = \{f \in CV_b(X, E) : vf(X) \subset G\},$$

where  $v \in V$  and  $G \in \mathcal{W}$ . We mention that, in the non-locally convex setting, the weighted function spaces  $CV_0(X, E)$  and  $CV_b(X, E)$  have been studied by several authors in recent years for a variety of problems; see e.g. [4, 5, 7, 8, 10, 13].

The following are some instances of weighted spaces.

1. If  $V = K^+(X) = \{\lambda\chi_X : \lambda > 0\}$ , the set of all non-negative constant functions on  $X$ , then  $CV_b(X, E) = C_b(X, E), CV_p(X, E) = C_p(X, E), CV_0(X, E) = C_0(X, E)$ , and  $w_V$  is the *uniform topology*  $\sigma$ .

2. If  $V = S_0^+(X)$ , the set of all non-negative upper semi-continuous functions on  $X$  which vanish at infinity, then  $CV_b(X, E) = CV_p(X, E) = CV_0(X, E) = C_b(X, E)$  and  $w_V$  is the *strict topology*  $\beta_0$ .

3. If  $V = K_c^+(X) = \{\lambda\chi_K : \lambda > 0 \text{ and } K \subset X, K \text{ compact}\}$ , then  $CV_b(X, E) = CV_p(X, E) = CV_0(X, E) = C(X, E)$  and  $w_V$  is the *compact-open topology*  $k$ .

4. If  $V = K_f^+(X) = \{\lambda\chi_A : \lambda > 0 \text{ and } A \subset X, A \text{ finite}\}$ , then  $CV_b(X, E) = CV_p(X, E) = CV_0(X, E) = C(X, E)$  and  $w_V$  is the *pointwise topology*  $p$ .

Clearly  $p \leq k$  on  $C(X, E)$  and  $k \leq \beta_0 \leq \sigma$  on  $C_b(X, E)$ . Moreover, the conditions on a Nachbin family  $V$  imply that  $p \leq w_V$ .

Let  $B(E, F)$  denote the algebra of all continuous linear mappings  $T$  from a TVS  $E$  into another  $F$ . For any collection  $\mathcal{A}$  of subsets of  $E$ ,  $B_{\mathcal{A}}(E, F)$  denotes the subspace of  $B(E, F)$  consisting of those  $T$  which are bounded on the members of  $\mathcal{A}$  together with the topology  $\tau_{\mathcal{A}}$  of uniform convergence on the elements of  $\mathcal{A}$ . This topology has a base of neighborhoods of 0 consisting of all sets of the form

$$M(A, U) := \{T \in B(E, F) : T(A) \subset U\},$$

where  $A \in \mathcal{A}$  and  $U$  is a neighborhood of 0 in  $F$ .

Finally, we will say that a net  $\{x_{\alpha} : \alpha \in I\}$  is a  $V$ -net if it is contained in  $S_{v,1} := \{x \in X : v(x) \geq 1\}$  for some  $v \in V$ . Following Bierstedt [1],  $X$  is said to be a  $V_{\mathbb{R}}$ -space if a function  $f : X \rightarrow \mathbb{R}$  is continuous whenever, for each  $v \in V$ , the restriction of  $f$  to  $S_{v,1}$  is continuous. If  $V = K(X)$ , then  $X$  is a  $V_{\mathbb{R}}$ -space means that  $X$  is a  $k_{\mathbb{R}}$ -space.

## 2 Main Results

For any  $x \in X$ , let  $\delta_x : CV_b(X, E) \rightarrow E$  denote the evaluation map  $\delta_x(f) = f(x)$  at  $x$ . Clearly,  $\delta_x \in B(CV_b(X, E), E)$ . Next, define the evaluation map  $\Delta : X \rightarrow B(CV_b(X, E), E)$  by  $\Delta(x) = \delta_x$ ,  $x \in X$ . If the subscript  $c$  in  $B_c(CV_b(X, E), E)$  stands for the topology of uniform convergence on precompact subsets of  $CV_b(X, E)$ , then one has the following lemma given in [10], see also [1, 12]

**Lemma 2.1** *The evaluation map  $\Delta : X \rightarrow B_c(CV_b(X, E), E)$  is continuous if and only if every precompact subset of  $CV_b(X, E)$  is equicontinuous. In particular, if  $X$  is  $V_{\mathbb{R}}$ -space, then every precompact subset of  $CV_b(X, E)$  is equicontinuous.*

The following theorem extends Theorem 2.1 of [12] to the general setting of TVS's.

**Theorem 2.2** *Let  $A$  be a subset of  $CV_0(X, E)$ . Then  $A$  is precompact whenever the following conditions hold.*

- i.  $A$  is equicontinuous.*
  - ii.  $A(x) = \{f(x) : f \in A\}$  is precompact in  $E$  for each  $x \in X$ .*
  - iii.  $vA$  vanishes at infinity on  $X$  for each  $v \in V$ . This is for each  $v \in V$  and  $G \in \mathcal{W}$ , there exists a compact set  $K \subset X$  such that  $v(y)f(y) \in G$  for all  $f \in A$  and  $y \in X \setminus K$ .*
- If  $X$  happens to be a  $V_{\mathbb{R}}$ -space, then the converse is also true.*

**Proof.** Suppose *i. – iii.* hold. Since  $CV_0(X, E) \subset C(X, E)$ , by *i.*,  $A$  is an equicontinuous subset of  $C(X, E)$ . Further, since, by *ii.*,  $A$  is  $p$ -precompact, it follows from ([14],

p. 289) that  $A$  is a precompact subset of  $(C(X, E), k)$ . To show that  $A$  is precompact in  $CV_0(X, E)$ , let  $v \in V$  and  $G \in \mathcal{W}$ . Choose a balanced  $H \in \mathcal{W}$  such that  $H + H \subset G$ . By *iii.*, there exists a compact  $K \subset X$  such that

$$v(y)f(y) \in H \text{ for all } f \in A \text{ and } y \in X \setminus K. \quad (1)$$

Since  $v$  is upper-semicontinuous,  $\|v\|_K = \sup\{v(y) : y \in K\} < \infty$ . But  $A$  is precompact in  $(C(X, E), k)$ . Then there exist  $h_1, \dots, h_n \in A$  such that

$$A \subset \bigcup_{i=1}^n (h_i + N(\chi_K, (\|v\|_k + 1)^{-1}H)). \quad (2)$$

We claim that

$$A \subset \bigcup_{i=1}^n \{h_i + N(v, G)\}.$$

Let  $f \in A$  and  $y \in X$ . If  $y \in K$ , by (2), there exists  $j \in \{1, \dots, n\}$  such that

$$v(y)(f(y) - h_j(y)) \in v(y)(\|v\|_k + 1)^{-1}H \subset H.$$

If  $y \in X \setminus K$ , then, for any  $i \in \{1, \dots, n\}$ , (1) gives

$$v(y)(f(y) - h_i(y)) = v(y)f(y) - v(y)h_i(y) \in H - H \subset G.$$

This establishes our claim, and so  $A$  is precompact in  $CV_0(X, E)$ . Now, Suppose  $X$  is a  $V_{\mathbb{R}}$ -space and that  $A$  is a precompact subset of  $CV_0(X, E)$ . Let us verify *i. – iii.* Since  $X$  is a  $V_{\mathbb{R}}$ -space, by (2.1),  $A$  is equicontinuous whereby *i.* On the other hand, since  $p \leq w_V$ ,  $H$  is  $p$ -precompact. Hence, for each  $x \in X$ ,  $A(x)$  is precompact in  $E$ . Whence *ii.* Finally, let  $v \in V$  and  $G \in \mathcal{W}$  and choose a balanced  $H \in \mathcal{W}$  with  $H + H \subset G$ . Since  $A$  is precompact, there exist  $h_1, \dots, h_n \in A$  such that

$$A \subset \bigcup_{i=1}^n (h_i + N(v, H)). \quad (3)$$

Put  $K = \cup_{i=1}^n \{y \in X : v(y)h_i(y) \notin H\}$ . Since  $h_i \in CV_0(X, E)$  for each  $i$ ,  $K$  is compact. Now, let  $f \in A$  and  $y \in X \setminus K$ . By (3), there exists  $i \in \{1, \dots, n\}$  such that  $f \in h_i + N(v, H)$ . Hence

$$v(y)f(y) = v(y)(f(y) - h_i(y)) + v(y)h_i(y) \in H + H \subset G.$$

Thus  $vA$  vanishes at infinity on  $X$ .

The following result is an extension of Theorem 2.2 of [12]. Following W.M. Ruess and W.H. Summers, we shall set, for any  $A \subset CV_p(X, E)$ ,  $v \in V$  and  $G \in \mathcal{W}$ ,

$$T_x(A, v, G) = \{y \in X : v(y)f(y) - v(x)f(x) \in G \text{ for all } f \in A\}, \quad x \in X.$$

**Theorem 2.3** Consider the following assertions:

**a.** (i)  $A$  is equicontinuous;

(ii)  $A(x)$  is precompact in  $E$  for each  $x \in X$ ,

(iii) given  $v \in V$  and  $G \in \mathcal{W}$ , there exists a compact set  $K \subset X$  such that  $\{T_x(A, v, G) : x \in K\}$  covers  $X$ .

**b.** (i)  $vA(X) = \{v(x)f(x) : x \in X, f \in A\}$  is precompact in  $E$  for each  $v \in V$ ;

(ii) given  $v \in V$  and  $G \in \mathcal{W}$ , there exists a finite set  $F \subset X$  such that  $\{T_x(A, v, G) : x \in F\}$  covers  $X$ .

**c.** (i)  $A(x)$  is precompact in  $E$  for each  $x \in X$ ;

(ii) given  $v \in V$  and  $G \in \mathcal{W}$ , there exists a finite set  $F \subset X$  such that  $\{T_x(A, v, G) : x \in F\}$  covers  $X$ .

**d.**  $A$  is precompact.

Then  $a. \implies b. \implies c. \implies d.$  If  $X$  is in addition a  $V_{\mathbb{R}}$ -space, then also  $c. \implies d.$

**Proof.**  $a. \implies b.$  Suppose  $a.$  holds. We first note that (i) and (ii) together imply, as in the proof of (2.2), that  $A$  is a precompact subset of  $(C(X, E), k)$ . We now verify  $b.$  (i) and  $b.$  (ii).

For  $b.$  (i), let  $v \in V$ ,  $G \in \mathcal{W}$  and choose a balanced  $H \in \mathcal{W}$  such that  $H + H + H + H \subset G$ . By  $a.$  (iii), there exists a compact  $K \subset X$  such that

$$X = \bigcup \{T_x(A, v, H) : x \in K\}. \quad (4)$$

Since  $A$  is precompact in  $(C(X, E), k)$ , there exist  $h_1, \dots, h_n \in A$  such that

$$A \subset \bigcup_{i=1}^n (h_i + N(\chi_k, (\|v\|_k + 1)^{-1}H)). \quad (5)$$

Moreover, since each  $vh_i(K)$  is precompact in  $E$ , there exist  $\{x_{ij}\}_{j=1}^{n_i} \subset K$  such that

$$vh_i(K) \subset \bigcup_{j=1}^{n_i} (v(x_{ij})h(x_{ij}) + H). \quad (6)$$

Now, fix any  $y \in X$  and  $f \in A$ . By (4),  $y \in T_x(A, v, H)$  for some  $x \in K$  and so

$$v(y)f(y) - v(x)f(x) \in H \text{ for all } f \in A. \quad (7)$$

By (5), there exists  $i \in \{1, \dots, n\}$  such that

$$(f - h_i)(K) \subset (\|v\|_k + 1)^{-1}H. \quad (8)$$

By (6), there exists  $j \in \{1, \dots, n_i\}$  such that

$$v(x)h_i(x) - v(x_{ij})h_i(x_{ij}) \in H. \quad (9)$$

By (7), (8) and (9)

$$\begin{aligned}
v(y)f(y) - v(x_{ij})h_i(x_{ij}) &= (v(y)f(y) - v(x)f(x)) + v(x)(f(x) - h(x)) \\
&\quad + (v(x)h_i(x) - v(x_{ij})h_i(x_{ij})) \\
&\in H + \frac{v(x)}{\|v\|_k + 1}H + H \subset G.
\end{aligned} \tag{10}$$

i.e.  $vA(X) \subset \bigcup_{i=1}^n \bigcup_{j=1}^{n_i} (v(x_{ij})h_i(x_{ij}) + G)$  and  $vA(X)$  is precompact in  $E$ .

For *b. (ii)*, let  $v \in V$  and  $G \in \mathcal{W}$ , and suppose these be same as in the proof of *b. (i)*. Also, let  $h_i$  and  $x_{ij}$  be as above. Set  $F = \bigcup_{i=1}^n \{x_{ij} : j = 1, \dots, n_i\}$ . Then, for any fixed  $y \in X$  and  $f \in A$ , (9) and (10) give

$$\begin{aligned}
v(y)f(y) - v(x_{ij})f(x_{ij}) &= (v(y)f(y) - v(x_{ij})h_i(x_{ij})) \\
&\quad + (v(x_{ij})h_i(x_{ij}) - v(x_{ij})f(x_{ij})) \\
&\in (H + H + H) + H \subset G;
\end{aligned}$$

that is,  $y \in T_x(A, v, G)$  with  $x \in F$ . Hence  $\{T_x(A, v, G) : x \in F\}$  covers  $X$ .

The implication *b.  $\implies$  c.* is trivial.

*c.  $\implies$  d.* : Suppose that *c.* holds. Fix any  $v \in V$  and  $G \in \mathcal{W}$  and choose a balanced  $H \in \mathcal{W}$  with  $H + H + H \subset G$ . By *c. (ii)* there exists a finite set  $F \subset X$  such that  $\{T_x(A, v, H) : x \in F\}$  covers  $X$ . By *c. (i)*,  $A$  is  $p$ -precompact, and so there exists  $h_1, \dots, h_n \in A$  such that

$$A \subset \bigcup_{i=1}^n (h_i + N(\chi_F, (\|v\|_F + 1)^{-1}H)). \tag{11}$$

We claim that  $A \subset \bigcup_{i=1}^n (h_i + N(v, G))$ . Fix any  $f \in A$ . By (11), there exists  $i \in \{1, \dots, n\}$  such that

$$(f - h_i)(F) \subset (\|v\|_F + 1)^{-1}H.$$

Then, for any  $y \in X$ ,  $y \in T_x(A, v, H)$  for some  $x \in F$  and so

$$\begin{aligned}
v(y)f(y) - v(y)h_i(y) &= (v(y)f(y) - v(x)) + v(x)(f(x) - h_i(x)) \\
&\quad + (v(x)h_i(x) - v(y)h_i(y)) \\
&\in H + \frac{v(x)}{\|v\|_F + 1}H - H \\
&\subset H + H + H \subset G.
\end{aligned}$$

This proves our claim; i.e., *d.* holds.

Now, assume that  $X$  is a  $V_{\mathcal{R}}$ -space and let us show that *d.  $\implies$  a.* Since  $A$  is a precompact subset of  $CV_p(X, E)$ , just as in the proof of (2.2), *a.(i)* and *a.(ii)* follow. To prove *a.(iii)*,

let  $v \in V$  and  $G \in \mathcal{W}$ . Choose a balanced  $H \in \mathcal{W}$  such that  $H + H + H \subset G$ . The precompactness of  $A$  gives  $h_1, \dots, h_n \in A$  such that

$$A \subset \bigcup_{i=1}^n (h_i + N(v, H)). \quad (12)$$

Now, consider the function  $h : X \rightarrow E^n$  defined by  $h(x) = (h_1(x), h_2(x), \dots, h_n(x))$ . This is a continuous function such that  $(vh)(X)$  is precompact, for it is contained in the product  $\prod_{i=1}^n (vh_i)(X)$  which is precompact. Hence for the neighborhood  $H^n$ , there exists a finite subset  $F$  of  $X$  such that

$$(vh)(X) = \bigcup_{x \in F} ((vh)(x) + H^n). \quad (13)$$

This gives

$$X \subset \bigcup_{x \in F} T_x(\{h_1, \dots, h_n\}, v, H). \quad (14)$$

We now show that  $\{T_x(A, v, G) : x \in F\}$  covers  $X$ . Fix  $y \in X$ . By (14),  $y \in T_x(\{h_i\}_{i=1}^n, v, H)$  for some  $x \in F$  and so

$$v(y)h_i(y) - v(x)h_i(x) \in H \quad \forall i = 1, \dots, n. \quad (15)$$

Given  $f \in A$ . By (12), there exists  $i \in \{1, \dots, n\}$  such that  $f - h_i \in N(v, H)$ ; this is

$$v(z)(f(z) - h_i(z)) \in H \quad \forall z \in X. \quad (16)$$

So, by (15) and (16),

$$\begin{aligned} v(y)f(y) - v(x)f(x) &= (v(y)f(y) - v(y)h_i(y)) \\ &\quad + (v(y)h_i(y) - v(x)h_i(x)) \\ &\quad + (v(x)h_i(x) - v(x)h(x)) \\ &\in H + H + H \subset G. \end{aligned}$$

Hence  $y \in T_x(A, v, G)$ ; i.e., *a.iii*) holds.

We mention that in the particular case of  $V = S_0^+(X)$ , (2.2) and (2.3) reduce to Theorem 3.6 of [3]. Further, the Corollaries 2.5.1(a), 2.5.2(a), 2.5.3, 2.5.4(a) of [12] remain valid in the above general setting and are stated as follows:

**Corollary 2.4** ([2], p. 81) *Let  $X$  be a  $k_{\mathbb{R}}$ -space and  $E$  a quasicomplete TVS. A subset  $A$  of  $(C(X, E), k)$  is relatively compact if and only if the following conditions hold.*

- (i) *A is equicontinuous on each compact subset of  $X$ ,*
- (ii) *A(x) is relatively compact in  $E$  for each  $x \in X$ .*

**Corollary 2.5** *Let  $X$  be a locally compact space and  $E$  a quasicomplete TVS. A subset  $A$  of  $(C_0(X, E), u)$  is relatively compact if and only if the following conditions hold.*

- (i)  $A$  is equicontinuous,
- (ii)  $A(x)$  is relatively compact in  $E$  for each  $x \in X$ ,
- (iii)  $A$  uniformly vanishes at infinity on  $X$  (i.e., for any  $G \in \mathcal{W}$ , there exists a compact set  $K \subset X$  such that  $f(y) \in G$  for all  $f \in A$  and  $y \in X \setminus K$ ).

**Corollary 2.6** ([3], Theorem 3.6) *Let  $X$  be a  $k_{\mathbb{R}}$ -space and  $E$  a quasicomplete TVS. A subset  $A$  of  $(C_b(X, E), \beta_0)$  is relatively compact if and only if the following conditions hold.*

- (i)  $A$  is equicontinuous on each compact subset of  $X$
- (ii)  $A(x)$  is relatively compact in  $E$  for every  $x \in X$ ,
- (iii)  $A$  is uniformly bounded (i.e.,  $A(X)$  is bounded in  $E$ ).

**Corollary 2.7** *Let  $E$  be a quasicomplete TVS. A subset  $A$  of  $(C_p(X, E), u)$  is relatively compact if and only if the following conditions hold.*

- (i)  $A(X)$  is relatively compact in  $E$ ,
- (ii) given  $G \in \mathcal{W}$ , there exists a finite open cover  $\{K_i : i = 1, \dots, n\}$  of  $X$  such that, for any  $i \in \{1, \dots, n\}$  and  $x, y \in K_i$ ,

$$f(x) - f(y) \in G, \quad \forall f \in A.$$

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