

## On saturation in conservative approximation\*

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### Abstract

In this paper we state a pointwise saturation result for sequences of linear operators that preserve the sign of the  $k$ -th derivative of the functions. We apply it to some well known sequences of operators.

### 1. Notation and introduction

Let  $A \subset \mathbb{R}$ ,  $i \in \mathbb{N}_0 = \mathbb{N} \cup \{0\}$ . As usual, we denote by  $C^i(A)$  the space of all real-valued  $i$ -times continuously differentiable functions defined on  $A$  and by  $D^i$  the  $i$ -th differential operator.  $C_B^i(A)$  denotes the subspace formed by the functions of  $C^i(A)$  which are bounded on  $A$ , and we write  $e_i$  for the polynomial  $e_i(t) = t^i$ . A function  $f \in C^i(A)$  is said to be  $i$ -convex if  $D^i f \geq 0$  on  $A$  and a linear operator is said to be  $i$ -convex if it maps  $i$ -convex functions onto  $i$ -convex functions.

Now let  $I$  be a closed real interval, let  $k \in \mathbb{N}_0$  and let  $L_n : C^k(I) \longrightarrow C^k(I)$  be a sequence of linear operators satisfying the following asymptotic condition:

A) there exist a sequence  $\lambda_n$  of real positive numbers, and a function  $p \in C^k(I)$  strictly positive on  $\text{Int}(I)$  such that for all  $g \in C_B^k(I)$ ,  $k + 2$ -times differentiable in some neighborhood of a point  $x \in \text{Int}(I)$ ,

$$\lim_{n \rightarrow +\infty} \lambda_n \left( D^k L_n g(x) - D^k g(x) \right) = D^k \left( p D^2 g \right) (x). \quad (1)$$

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Some recent papers have proved that this formula is satisfied for many known operators (see [1], [4], [7]). It informs that the speed of convergence of  $D^k L_n g(x) - D^k g(x)$  to 0 cannot overcome in general the one of  $\lambda_n^{-1}$ . Those functions  $f$  that satisfy  $D^k L_n f(x) - D^k f(x) = o(\lambda_n^{-1})$  for  $x \in (a, b)$  with  $a, b \in \text{Int}(I)$  form the trivial class for the local saturation problem of  $D^k L_n$ , while the functions that satisfy  $D^k L_n f(x) - D^k f(x) = O(\lambda_n^{-1})$  for  $x \in (a, b)$  form the so-called saturation class. Recently, in [5] the authors have found these classes assuming also the following shape preserving property:

B) for all  $n \in \mathbb{N}$ ,  $L_n$  is  $k$ -convex.

They have extended the results obtained by Mühlbach [11] for the case  $k = 0$ , taking into account the outstanding work by Lorent and Schumaker [9] in 1972. Simultaneously, Berens [3] dealt with this matter from a more general point of view but also just for  $k = 0$ . Here the basic tools were convexity arguments through the use of the theory of extended complete Tchebycheff systems (ECT-Systems) and a generalization of the parabola technique introduced by Bajanski and Bojanić [2].

In the present paper we assume A) and B) and prove a pointwise saturation result for  $D^k L_n$  that extends this last one in the sense of considering  $k > 0$ . We will also apply it in the last section to the well-known operators of Bernstein and Szász-Mirakjan. Firstly, we prove the general formulation of the parabola technique we shall use here.

**Lemma 1** *Let  $0 = Ly := D^2y + a_1(t)D^1y + a_2(t)y = 0$  be a second-order linear differential equation with  $a_1, a_2 \in C(I)$  and assume that it has a unique solution taking any two given real values at any two given points within  $\text{Int}(I)$ . Let  $g \in C(I)$  and  $t_1, t_2 \in \text{Int}(I)$ . If  $f \in C(I)$  verifies that  $f(t_1) = f(t_2) = 0$  and  $f(t_0) > 0$  for some  $t_0 \in (t_1, t_2)$ , then there exist a real constant  $\alpha < 0$  and a solution of the previous differential equation,  $\tilde{y}$ , such that for all  $t \in [t_1, t_2]$ ,  $\alpha g(t) + \tilde{y}(t) > f(t)$  and for some  $s \in (a, b)$ ,  $\alpha g(s) + \tilde{y}(s) = f(s)$ .*

**Proof** Let  $L_g$  be the unique solution of  $Ly = 0$  satisfying  $L_g(t_i) = g(t_i)$ ,  $i = 1, 2$ , let  $y_0$  be a solution of  $Ly = 0$  satisfying  $y_0(t) > 0 \forall t \in [t_1, t_2]$  (whose existence is guaranteed taking into account that  $t_1, t_2 \in \text{Int}(I)$ ), and let  $\epsilon > 0$  be sufficiently small so that  $f(t_0) - \epsilon(L_g(t_0) - g(t_0)) > 0$ . Then the function

$$\frac{f - \epsilon(L_g - g)}{y_0}$$

is continuous in  $[t_1, t_2]$ , it vanishes at the end points of this interval and it is strictly positive at the point  $t_0$ , so it reaches a maximum value, say  $M$ , at a point  $s \in (t_1, t_2)$ . Consequently, for all  $t \in [t_1, t_2]$

$$\epsilon(L_g(t) - g(t)) + My_0(t) \geq f(t)$$

and

$$\epsilon(L_g(s) - g(s)) + My_0(s) = f(s).$$

Now the proof is over taking  $\alpha = -\epsilon$  and  $\tilde{y} = \epsilon L_g + My_0$ .  $\square$

## 2. The results

Along this section we assume that the operators  $L_n$  defined in Section 1. satisfy A) and B). In [5] we proved the following result

**Lemma 2** a) For  $k \in \mathbb{N}$  the ordinary linear differential equation

$$D^k(pD^2y) \equiv 0, \tag{2}$$

has a fundamental system of solutions of the form  $\{e_0, \dots, e_{k-1}, y_0, y_1\}$ , and using the change of variable  $z = D^k y$  it can be reduced to

$$D^2z + \frac{kD^1p}{p}D^1z + \frac{k(k-1)D^2p}{2p}z \equiv 0 \tag{3}$$

( $p$  is necessarily a polynomial of degree less than or equal to 2).

b) If  $f \in C_B^k(I)$  is a solution of (2) on some neighborhood of a point  $x \in \text{Int}(I)$ , then

$$D^k L_n f(x) - D^k f(x) = o(\lambda_n^{-1}).$$

c) Let  $f, g \in C_B^k(I)$ . If  $D^k f \leq D^k g$  on some neighborhood of a point  $x \in \text{Int}(I)$ , then

$$D^k L_n f(x) \leq D^k L_n g(x) + o(\lambda_n^{-1}).$$

In the sequel, if not specified in other sense, solutions of equation (2) and (3) are understood on  $\text{Int}(I)$ .

Take  $a, b \in \text{Int}(I)$  with  $a < b$  and assume that (3) has a fundamental system of solutions, say  $\{z_0, z_1\}$ , which form an ECT-System on  $(a, b)$ . We write it as in [6], from the functions  $w_0$  and  $w_1$ :

$$z_0(t) = w_0(t), \quad z_1(t) = w_0(t) \int_a^t w_1(s) ds. \tag{4}$$

The next lemma shows the relation between convexity respect to this ECT-System and approximation by  $D^k L_n$ .

**Lemma 3** Let  $f \in C^k(I)$ . If

$$\limsup_{n \rightarrow \infty} \lambda_n (D^k L_n f(t) - D^k f(t)) \geq 0, \quad t \in (a, b),$$

then  $D^k f$  is convex on  $(a, b)$  with respect to  $z_0, z_1$ .

**Proof** Assuming the contrary, there exist  $a < t_1 < t_0 < t_2 < b$  such that  $D^k f(t_0) > z(t_0)$ , being  $z = z(t)$  the unique solution of (3) satisfying  $z(t_i) = D^k f(t_i)$ ,  $i = 1, 2$ . Let us apply Lemma 1 to (3) and  $D^k f - z$ , with  $g = D^k w$ , being  $w \in C^k(I)$  such that  $D^2 w(t) = e_k(t)/p(t)$  for all  $t \in [t_1, t_2]$ . Then there exist a solution of (3), say  $\tilde{z}$ , and a constant  $\alpha < 0$  verifying that for all  $t \in [t_1, t_2]$

$$D^k f(t) - z(t) \leq \alpha D^k w(t) + \tilde{z}(t)$$

and for some  $s \in (t_1, t_2)$

$$D^k f(s) - z(s) = \alpha D^k w(s) + \tilde{z}(s).$$

Now if we take  $y, \tilde{y} \in C_B^k(I)$ , solutions of (2) on  $(t_1, t_2)$  such that  $D^k y(t) = z(t)$  and  $D^k \tilde{y}(t) = \tilde{z}(t)$ , then using c), Lemma 2,

$$\begin{aligned} \lambda_n \left( D^k L_n f(s) - D^k f(s) \right) &\leq \alpha \lambda_n \left( D^k L_n w(s) - D^k w(s) \right) \\ + \lambda_n \left( D^k L_n \tilde{y}(s) - D^k \tilde{y}(s) \right) &+ \lambda_n \left( D^k L_n y(s) - D^k y(s) \right) + o(1). \end{aligned}$$

Using b), Lemma 2 for  $y$  and  $\tilde{y}$  and the asymptotic condition A) for  $w$  we obtain

$$\lambda_n \left( D^k L_n f(s) - D^k f(s) \right) \leq \alpha k! + o(1)$$

what is a contradiction that ends the proof.  $\square$

Now we prove the main result. We shall obtain some information about functions  $f$  that verify  $D^k L_n f(x) - D^k f(x) = o(\lambda_n^{-1})$  and  $D^k L_n f(x) - D^k f(x) = O(\lambda_n^{-1})$  for  $x \in (a, b)$ , though we shall consider a more general framework. For this purpose we define  $\varphi_x(t) := (t - x)^{k+2}/(k+2)!$  and  $\mu_n(x) := D^k L_n \varphi_x(x)$ . Notice that from A)  $\mu_n(x) = O(\lambda_n^{-1})$ , specifically

$$\lambda_n \mu_n(x) = p(x) + o(1). \quad (5)$$

Firstly we prove the following technical lemma which shall be used in the proof of Theorem 1. In both of them we use the functions  $w_2 := 1/w_0 w_1$  and  $W_2(t) := \int_a^t w_2(s) ds$ .

**Lemma 4** *Let  $h \in C[a, b]$  and  $H \in C^k(I)$  be such that for all  $t \in (a, b)$ ,  $D^k H(t) = w_0(t) \int_a^t h(s) w_1(s) ds$ . Then, for  $x \in (a, b)$ ,*

$$\limsup_{n \rightarrow \infty} \frac{D^k L_n H(x) - D^k H(x)}{\mu_n(x)} \leq \limsup_{t \rightarrow x} \frac{h(t) - h(x)}{W_2(t) - W_2(x)}$$

and

$$\liminf_{t \rightarrow x} \frac{h(t) - h(x)}{W_2(t) - W_2(x)} \leq \liminf_{n \rightarrow \infty} \frac{D^k L_n H(x) - D^k H(x)}{\mu_n(x)}.$$

**Proof** We shall only prove the first inequality; the other one works similarly. Let  $x \in (a, b)$ . We assume that there exists a real number  $m$  such that

$$\limsup_{t \rightarrow x} \frac{h(t) - h(x)}{W_2(t) - W_2(x)} < m$$

because if this is not the case there is nothing to prove. Then for some  $\delta > 0$  whenever  $|t - x| < \delta$ ,

$$\frac{h(t) - h(x)}{W_2(t) - W_2(x)} < m.$$

So for a sufficiently small  $\delta$  we have

$$\frac{h(t) - h(x)}{(t - x)w_2(x)} < m.$$

Multiplying by  $w_1(t)$  and integrating we have

$$\int_x^t (h(s) - h(x)) w_1(s) ds < mw_2(x) \int_x^t (s - x) w_1(s) ds,$$

which, taking into account that

$$\frac{D^k H(t)}{w_0(t)} - \frac{D^k H(x)}{w_0(x)} = \int_x^t h(s) w_1(s) ds,$$

provides

$$\frac{D^k H(t)}{w_0(t)} - \frac{D^k H(x)}{w_0(x)} - h(x) \int_x^t w_1(s) ds < mw_2(x) \int_x^t (s - x) w_1(s) ds.$$

Multiplying now by  $w_0(t)$  and considering  $W_1(t) := \int_a^t w_1(s) ds$  we obtain

$$\begin{aligned} D^k H(t) - \frac{D^k H(x) w_0(t)}{w_0(x)} - h(x) (z_1(t) - W_1(x) w_0(t)) \\ < mw_2(x) w_0(t) \int_x^t (s - x) w_1(s) ds. \end{aligned}$$

Equivalently, taking  $y_0, y_1, Y \in C^k(I)$  such that their  $k$ -th derivatives coincide respectively with  $z_0, z_1$  and  $w_2(x) w_0(t) \int_x^t (s - x) w_1(s) ds$  in the neighborhood of the point  $x$  we are dealing with,

$$D^k H(t) - \frac{D^k H(x) D^k y_0(t)}{w_0(x)} - h(x) (D^k y_1(t) - W_1(x) D^k y_0(t)) < m D^k Y(t).$$

Applying c), Lemma 2

$$\begin{aligned} D^k L_n H(x) - \frac{D^k H(x) D^k L_n y_0(x)}{w_0(x)} - h(x) (D^k L_n y_1(x) - W_1(x) D^k L_n y_0(x)) \\ \leq m D^k L_n Y(x) + o(\lambda_n^{-1}). \end{aligned}$$

Introducing the zero terms  $-D^k H(x) + \frac{D^k H(x)}{z_0(x)} D^k y_0(x)$  and  $-D^k y_1(x) + D^k y_0(x) W_1(x)$  (notice that  $z_1(x) = z_0(x) W_1(x)$ ), and regrouping,

$$\begin{aligned} & D^k L_n H(x) - D^k H(x) - \frac{D^k H(x)}{z_0(x)} (D^k L_n y_0(x) - D^k y_0(x)) \\ & - h(x) (D^k L_n y_1(x) - D^k y_1(x) - W_1(x) (D^k L_n y_0(x) - D^k y_0(x))) \\ & \leq m D^k L_n Y(x) + o(\lambda_n^{-1}). \end{aligned}$$

Applying b), Lemma 2 to the functions  $y_0$  and  $y_1$ , and hypothesis A) to  $Y$ ,

$$\begin{aligned} \lambda_n (D^k L_n H(x) - D^k H(x)) & \leq m D^k (p D^2 Y)(x) + o(1) \\ & = m p(x) w_2(x) w_0(x) w_1(x) + o(1) = m p(x) + o(1), \end{aligned}$$

where for the last equalities we have done some calculations taking into account the definitions of  $Y, w_2$  and that  $p$  is a polynomial of degree less than or equal to 2. Finally, using (5) and taking  $\limsup_{n \rightarrow \infty}$  we obtained

$$\limsup_{n \rightarrow \infty} \frac{D^k L_n H(x) - D^k H(x)}{\mu_n(x)} \leq m,$$

and the proof is over.  $\square$

**Theorem 1** *Let  $f \in C^k(I)$  and suppose that  $\psi$  is a finitely valued function in  $L_1[a, b]$  for which*

$$\liminf_{n \rightarrow \infty} \frac{D^k L_n f(x) - D^k f(x)}{\mu_n(x)} \leq \psi(x) \leq \limsup_{n \rightarrow \infty} \frac{D^k L_n f(x) - D^k f(x)}{\mu_n(x)}.$$

*Then there exist two constants  $\alpha_0$  and  $\alpha_1$  such that for all  $t \in (a, b)$ ,*

$$D^k f(t) = \alpha_0 z_0(t) + \alpha_1 z_1(t) + w_0(t) \int_a^t w_1(s) \int_a^s \psi(v) w_2(v) dv ds.$$

**Proof** Let  $G \in C^k(I)$  such that for all  $t \in (a, b)$

$$D^k G(t) = D^k f(t) - w_0(t) \int_a^t w_1(s) \int_a^s \psi(v) w_2(v) dv ds.$$

We shall prove that  $D^k G$  is convex and concave in  $(a, b)$  with respect to  $z_0$  and  $z_1$ .

For  $q \in \mathbb{N}$  let  $m_q$  and  $M_q$  be respectively the minor and major functions of  $\psi$  with respect to  $w_2$ , such that

$$\begin{aligned} \left| m_q(t) - \int_a^t \psi(s) w_2(s) ds \right| & < \frac{1}{q}, \quad t \in (a, b), \\ \left| M_q(t) - \int_a^t \psi(s) w_2(s) ds \right| & < \frac{1}{q}, \quad t \in (a, b), \end{aligned}$$

whose existence is well known from the theory of Lebesgue integration (see for instance [12]). In particular it follows that

$$\limsup_{t \rightarrow x} \frac{m_q(t) - m_q(x)}{W_2(t) - W_2(x)} \leq \psi(x) \leq \liminf_{t \rightarrow x} \frac{M_q(t) - M_q(x)}{W_2(t) - W_2(x)}.$$

From Lemma 4 and the hypothesis, if we consider  $\tilde{m}_q \in C^k(I)$  such that for all  $t \in (a, b)$   $D^k \tilde{m}_q(t) = w_0(t) \int_a^t m_q(s) w_1(s) ds$ , we have that

$$\begin{aligned} \limsup_{n \rightarrow \infty} \frac{D^k L_n \tilde{m}_q(x) - D^k \tilde{m}_q(x)}{\mu_n(x)} &\leq \limsup_{t \rightarrow x} \frac{m_q(t) - m_q(x)}{W_2(t) - W_2(x)} \\ &\leq \psi(x) \leq \limsup_{n \rightarrow \infty} \frac{D^k L_n f(x) - D^k f(x)}{\mu_n(x)}, \end{aligned}$$

so

$$\limsup_{n \rightarrow \infty} \frac{D^k L_n (f - \tilde{m}_q)(x) - D^k (f - \tilde{m}_q)(x)}{\mu_n(x)} \geq 0.$$

From (5) and Lemma 3, we deduce that for all  $q \in \mathbb{N}$   $D^k (f - \tilde{m}_q)$  is convex in  $(a, b)$  with respect to  $z_0$  and  $z_1$ . Letting  $q$  tend to infinity we conclude that this also holds for  $D^k G$ . Analogously from  $M_q$  we obtain that  $D^k G$  is concave in  $(a, b)$  with respect to  $z_0$  and  $z_1$ .  $\square$

**Remark** This theorem recovers the converse result of b), Lemma 2 that was stated in [5]. Indeed, if  $D^k L_n f(x) - D^k f(x) = o(\lambda_n^{-1})$ , then  $D^k L_n f(x) - D^k f(x) = o(\mu_n(x))$  and the theorem applies with  $\psi \equiv 0$ .

### 3. Applications

In this section we apply the previous result to the Bernstein and Szász-Mirakjan operators defined as follows respectively on  $C[0, 1]$  and  $C[0, \infty)$  :

$$\begin{aligned} B_n f(t) &= \sum_{p=0}^n f\left(\frac{p}{n}\right) \binom{n}{p} t^p (1-t)^{n-p}, \\ S_n f(t) &= e^{-nt} \sum_{p=0}^{\infty} f\left(\frac{p}{n}\right) \frac{n^p t^p}{p!}. \end{aligned}$$

It is very well-known (see [8], [10]) that they are convex of any order, i.e. B) holds true for any value of  $k \in \mathbb{N}_0$ . The validity of A) for  $B_n$  with  $k = 0$ ,  $\lambda_n = 2n$ ,  $p(t) = t(1-t)$ , and for  $S_n$  with  $k = 0$ ,  $\lambda_n = 2n$ ,  $p(t) = t$  follows from classical results of Voronovskaya [14] and Szász [13]. Specifically, under the aforementioned conditions,

$$\lim_{n \rightarrow +\infty} 2n (B_n g(x) - g(x)) = x(1-x) D^2 g(x), \quad (6)$$

and

$$\lim_{n \rightarrow +\infty} 2n(S_n g(x) - g(x)) = xD^2 g(x). \quad (7)$$

Roughly speaking, one can apply the differential operator  $D^k$  for any  $k \in \mathbb{N}$  to both sides of the identities, what yields that A) holds true for  $B_n$ ,  $S_n$  and all  $k \in \mathbb{N}$  taking for  $\lambda_n$  and  $p$  the corresponding values above (see [4], [7], [1]).

Hence we can apply our result to these operators. The following table contains for each operator and for  $k > 0$  the values of  $\lambda_n$  and  $p(t)$ , and a choice for  $w_0(t)$  and  $w_1(t)$ . We do not apply our result to the case  $k = 0$  because this can be done from [3].

	$B_n$	$S_n$
$\lambda_n$	$2n$	$2n$
$p(t)$	$t(1-t)$	$t$
$w_0(t)$	$1/t^{k-1}$	$1$
$w_1(t)$	$t^{k-2}/(1-t)^k$	$1/t^k$
$w_2(t)$	$t(1-t)^k$	$t^k$

From Theorem 1, the following corollaries are easily obtained.

**Corollary 1** *Let  $k \in \mathbb{N}$ ,  $0 < a < b < 1$ ,  $f \in C^k[0, 1]$ ,  $\mu_n(x) = D^k B_n \varphi_x(x)$  and suppose that  $\psi$  is a finitely valued function in  $L_1[a, b]$  such that*

$$\liminf_{n \rightarrow \infty} \frac{D^k B_n f(x) - D^k f(x)}{\mu_n(x)} \leq \psi(x) \leq \limsup_{n \rightarrow \infty} \frac{D^k B_n f(x) - D^k f(x)}{\mu_n(x)}.$$

*Then there exist two constants  $\alpha_0$  and  $\alpha_1$  such that for all  $t \in (a, b)$ , one has*

$$D^1 f(t) = \alpha_0 + \alpha_1 \log \frac{t}{1-t} + \int_a^t \frac{1}{s(1-s)} \int_a^s \psi(v)v(1-v)dv ds,$$

*for  $k = 1$  and*

$$D^k f(t) = \frac{\alpha_0}{t^{k-1}} + \frac{\alpha_1}{(1-t)^{k-1}} + \frac{1}{t^{k-1}} \int_a^t \frac{s^{k-2}}{(1-s)^k} \int_a^s \psi(v)v(1-v)^k dv ds,$$

*for  $k > 1$ .*

**Corollary 2** *Let  $k \in \mathbb{N}$ ,  $0 < a < b$ ,  $f \in C_B^k[0, \infty)$ ,  $\mu_n(x) = D^k S_n \varphi_x(x)$  and suppose that  $\psi$  is a finitely valued function in  $L_1[a, b]$  such that*

$$\liminf_{n \rightarrow \infty} \frac{D^k S_n f(x) - D^k f(x)}{\mu_n(x)} \leq \psi(x) \leq \limsup_{n \rightarrow \infty} \frac{D^k S_n f(x) - D^k f(x)}{\mu_n(x)}.$$

*Then there exist two constants  $\alpha_0$  and  $\alpha_1$  such that for all  $t \in (a, b)$ , one has*

$$D^1 f(t) = \alpha_0 + \alpha_1 \log t + \int_a^t \frac{1}{s} \int_a^s \psi(v)v dv ds,$$

*for  $k = 1$  and*

$$D^k f(t) = \alpha_0 + \frac{\alpha_1}{t^{k-1}} + \int_a^t \frac{1}{s^k} \int_a^s \psi(v)v^k dv ds,$$

*for  $k > 1$ .*



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